

IEEE Robotics and Automation Society

2025 IEEE International Conference on Robotics and Automation 2025 ICRA

Third Place of Robotic Grasping and Manipulation Competition, Picking from Clutter Track

is presented to

AR Lab NCSU Team, North Carolina State University Prem Raj, Lirong Xiang, Weilong He, Zhenghua Zhang, Shengdao Du

Atlanta, Georgia, 19 – 23 May 2025

Nancy Amato 2025 ICRA Chair

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